<del></del>	r ———						
Туре	L #	Hits	Search Text	DBs	Time Stamp	Comment	
IS&R	L1	60499	(382/100,190,199,201) .CCLS. or (("348") or ("351")).CLAS.	USPA T	2004/06/1 8 20:03		
BRS	L2	26636	1 and detect\$4	USPA T	2004/06/1 8 20:03		
BRS	L3	6896	_	USPA T	2004/06/1 8 20:04		
BRS	L4	6106	3 and (calculat\$4 or comput\$4 or measur\$6)	T	8 20:04		
BRS	L5	2475	4 and extract\$5	USPA T	2004/06/1 8 20:15		
BRS	L6	810	5 and target\$4	USPA T	2004/06/1 8 20:04		
BRS	L7	744	6 and stor\$4	USPA T	2004/06/1 8 20:05		
BRS	L8	696	7 and (photograph\$4 or pictur\$4 or featur\$4)	USPA T	2004/06/1 8 20:06		
BRS	L9	628	8 and ( camera\$4 or video\$4 or CCD)	USPA T	2004/06/1 8 20:06		
BRS	L10	607	9 and imag\$4	USPA T	2004/06/1 8 20:06	1	
BRS	L11	334	10 and intensit\$4	USPA T	2004/06/1 8 20:07		
BRS	L12	58	11 and templat\$4	USPA T	2004/06/1 8 20:07		
BRS	L13	17	12 and narrow\$4	USPA T	2004/06/1 8 20:07		
BRS	L14	10	13 and color\$4	USPA T	2004/06/1 8 20:07		
BRS	L15	10	14 and match\$4	USPA T	2004/06/1 8 20:09		
BRS	L16	40697		USPA T	2004/06/1 8 20:10		
BRS	L17	•	•	USPA T	2004/06/1 8 20:10		
BRS	L18	31	4 and 17	USPA T	2004/06/1 8 20:10		
BRS	L19	14	18 and ((detect\$4 or scan\$4) near4 (parameter\$4))	USPA T	2004/06/1 8 20:12		
BRS	L20	1076	16 and ((detect\$4 or scan\$4) near4 (parameter\$4))	USPA T	2004/06/1 8 20:13		
BRS	L21	458	20 and updat\$4	USPA T	2004/06/1 8 20:13		
BRS	L22	133	21 and ( detect\$4 near4 position\$4)	USPA T	2004/06/1 8 20:13		
BRS	L23	12	22 and ( target\$4 near3 imag\$4)	USPA T	2004/06/1 8 20:14		
	IS&R  BRS  BRS  BRS  BRS  BRS  BRS  BRS	IS&R L1  BRS L4  BRS L5  BRS L6  BRS L6  BRS L7  BRS L9  BRS L10  BRS L10  BRS L11  BRS L11  BRS L12  BRS L13  BRS L11  BRS L15  BRS L11  BRS L13  BRS L11  BRS L13  BRS L11  BRS L11  BRS L15  BRS L11  BRS L11  BRS L12  BRS L12  BRS L12	IS&R       L1       60499         BRS       L2       26636         BRS       L3       6896         BRS       L4       6106         BRS       L5       2475         BRS       L6       810         BRS       L7       744         BRS       L9       628         BRS       L10       607         BRS       L11       334         BRS       L12       58         BRS       L13       17         BRS       L14       10         BRS       L15       10         BRS       L16       40697         BRS       L17       1247         BRS       L19       14         BRS       L19       14         BRS       L20       1076         BRS       L21       458         BRS       L21       458         BRS       L23       13         BRS       L23       13         BRS       L23       13	ISER L1 60499 (382/100,190,199,201) CCLS. or (("348") or ("351")).CLAS.  BRS L2 26636 1 and detect\$4  BRS L3 6896 2 and parameter\$4  BRS L4 6106 3 and (calculat\$4 or comput\$4 or measur\$6)  BRS L5 2475 4 and extract\$5  BRS L6 810 5 and target\$4  BRS L7 744 6 and stor\$4  BRS L8 696 7 and (photograph\$4 or pictur\$4 or featur\$4)  BRS L9 628 8 and (camera\$4 or video\$4 or CCD)  BRS L10 607 9 and imag\$4  BRS L11 334 10 and intensit\$4  BRS L12 58 11 and templat\$4  BRS L13 17 12 and narrow\$4  BRS L14 10 13 and color\$4  BRS L15 10 14 and match\$4  BRS L16 40697 Specifi\$4 near4 point\$4  BRS L17 1247 near4 (specifi\$4 near4 point\$4)  BRS L18 31 4 and 17  BRS L19 14 sand (detect\$4 or scan\$4 near4 point\$4)  BRS L19 16 and (detect\$4 or scan\$4 (parameter\$4))  BRS L20 1076 (can\$4) near4 (parameter\$4)  BRS L21 458 20 and updat\$4  BRS L22 133 21 and detect\$4 or scan\$4 near4 point\$4)	IS&R         L1         60499 (382/100,199,199,201) (USPA T)           BRS         L2         26636 l and detect\$4         USPA T T           BRS         L3         6896 2 and parameter\$4 T T         USPA T T           BRS         L3         6896 2 and parameter\$4 T T         USPA T T           BRS         L4         6106 3 and (calculat\$4 or USPA T T         USPA T T           BRS         L5         2475 4 and extract\$5         USPA T T           BRS         L6         810 5 and target\$4         USPA T T           BRS         L6         810 5 and target\$4         USPA T T           BRS         L6         810 5 and target\$4         USPA T T           BRS         L6         810 5 and target\$4         USPA T T           BRS         L6         810 5 and target\$4         USPA T T           BRS         L8         696 or pictur\$4 or \$1 T T         USPA T T           BRS         L9         628 8 and (camera\$4 or USPA T T         USPA T T           BRS         L10 607 9 and imag\$4         USPA T T           BRS         L11 334 10 and intensit\$4         USPA T T           BRS         L12 58 11 and templat\$4         USPA T T           BRS         L14 10 13 and color\$4         USPA T T	Type   L #   Hits   Search Text   DBs   Stamp	

	Type	L #	Hits	Search Text	DBs	Time Stamp	Commen ts	Error Definition	Er ro rs
1	BRS	L1	1417 6	((detect\$6) near4 ( specific\$4 adj "2" points))	USPA T	15:00			0
2	BRS	L2	117	((detect\$6) near4 ( specific\$4 adj2 points))	USPA T	13:27		,	0
3	BRS	L3	7	2 and ( detect\$4 near4 parameter\$4)	USPA T	15:00			0
4	BRS	L4	0	3 and ( target\$4 near4 image)	USPA T	723 15:01			0
5	BRS	L6	0	5 and imag\$4	USPA T	/23 13:29			0
6	BRS	L5	2	3 and (target\$4)	USPA T	/23 13:28			0
7	BRS	L7	2	3 and imag\$4	USPA T	13:30			0
8	BRS	L8	872	1 and ( detect\$4 near4 parameter\$4)	USPA T	/23 13:29			0
9	BRS	L9	71	((detect\$6) near4 ( specific\$4 adj points))	USPA T	13:30			0
10	BRS	L10	7	9 and ( detect\$4 near4 parameter\$4)	USPA T	/23 13:30			0
11	BRS	L11	0	10 and ( target\$4 near4 image)	USPA T	13:30			0
12	BRS	L12	2	10 and imag\$4	USPA T	/23 13:31			0
13	BRS	L13	184	((detect\$6) near4 ( specific\$4 near4 points))	USPA T	/23 13:31			0
14	BRS	L14	16	13 and ( detect\$4 near4 parameter\$4)	USPA T	/23 13:31			0
15	BRS	L15	2	14 and ( target\$4 near4 image)	USPA T	13:35			0
16	BRS	L16	2	15 and ( detect\$4 near4 position\$4)	USPA T	/23 13:35			0
17	BRS	L18	2	16 and ( detect\$5 near4 point\$4)	USPA T	2004/02 /23 13:36			0

	Туре	L #	Hits	Sea	arch Text	DBs	Time Stamp	Commen	Error Definition	Er ro rs
33	BRS	L33	9	32 and	acrocabyi	Т	2004/03 /12 10:44			0
34	BRS	L34	55	28 and	acrocaby r	Т	2004/03 /12 10:44			0
35	BRS	L35	43	34 and		T	2004/03 /12 10:44			0
36	BRS	L36	39	35 and	compar\$4	USPA T	2004/03 /12 10:45			0



## PALM INTRANET

Day: Friday Date: 6/18/2004 Time: 19:54:22

## **Inventor Name Search Result**

Your Search was:

Last Name = SATOH

First Name = KIYOHIDE

Application#	Patent#	Status	Date Filed	Title	Inventor Name 16
10752487	Not Issued	020	01/08/2004	POSITION/ORIENTATION MEASUREMENT METHOD, AND POSITION/ORIENTATION MEASUREMENT APPARATUS	SATOH, KIYOHIDE
10670285	Not Issued	030	09/26/2003	INFORMATION PROCESSING METHOD AND INFORMATION PROCESSING APPARATUS	SATOH, KIYOHIDE
10660637	Not Issued	030	09/12/2003	IMAGE DISPLAY APPARATUS, IMAGE DISPLAY METHOD, MEASUREMENT APPARATUS, MEASUREMENT METHOD, INFORMATION PROCESSING METHOD, INFORMATION PROCESSING APPARATUS, AND IDENTIFICATION METHOD	SATOH, KIYOHIDE
10644829	Not Issued	030	08/21/2003	IMAGE PROCESSING DEVICE AND METHOD THEREFOR AND PROGRAM CODES, STORING MEDIUM	SATOH, KIYOHIDE
10390739	Not Issued	093	03/19/2003	SENSOR CALIBRATION APPARATUS, SENSOR CALIBRATION METHOD, PROGRAM, STORAGE MEDIUM, INFORMATION PROCESSING METHOD, AND INFORMATION PROCESSING APPARATUS	SATOH, KIYOHIDE
10351326	Not Issued	030	01/27/2003	POSITION AND ORIENTATION DETERMINATION METHOD AND APPARATUS AND STORAGE MEDIUM	SATOH, KIYOHIDE
10278947	Not Issued	030	10/24/2002	IMAGE DISPLAY APPARATUS, METHOD AND RECORDING MEDIUM	SATOH, KIYOHIDE

10274200	Not Issued	041	10/21/2002	IMAGE DISPLAY APPARATUS AND METHOD, AND STORAGE MEDIUM	1
09818602	Not Issued	041	03/28/2001	POSITION AND ORIENTATION DETERMINING METHOD AND APPARATUS AND STORAGE MEDIUM	SATOH, KIYOHIDE
09818600	Not Issued	092	03/28/2001	INFORMATION PROCESSING APPARATUS, MIXED REALITY PRESENTATION APPARATUS, METHOD THEREOF, AND STORAGE MEDIUM	SATOH, KIYOHIDE
09817037	Not Issued	030	03/27/2001	SPECIFIC POINT DETECTING METHOD AND DEVICE	SATOH, KIYOHIDE
09816072	6633304	150	03/26/2001	MIXED REALITY PRESENTATION APPARATUS AND CONTROL METHOD THEREOF	SATOH, KIYOHIDE
09658463	Not Issued	083	09/08/2000	AUGMENTED REALITY PRESENTATION APPARATUS AND METHOD,AND STORAGE MEDIUM	SATOH, KIYOHIDE
09654774	Not Issued	168	09/05/2000	AUGMENTED REALITY PRESENTATION SYSTEM, HEAD-MOUNTED DISPLAY DEVICE, CONTROL METHOD FOR HEAD-MOUNTED DISPLAY DEVICE, AND IMAGE GENERATION METHOD FOR HEAD-MOUNTED DISPLAY DEVICE	SATOH, KIYOHIDE
09648295	Not Issued	161	08/28/2000	DEPTH INFORMATION MEASUREMENT APPARATUS AND MIXED REALITY PRESENTATION SYSTEM	SATOH, KIYOHIDE
09506084	Not Issued	071	02/17/2000	GAME APPARATUS FOR MIXED REALITY SPACE, IMAGE PROCESSING METHOD THEREOF, AND PROGRAM STORAGE MEDIUM	SATOH, KIYOHIDE

Inventor Search Completed: No Records to Display.

	Last Name	First Name	
Search Another:	Satoh	Kiyohide	
Inventor		Search	

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NL = Journal or Magazine CNF = Conference STD = Standard						
Imaging below the diffraction limit: a statistical analysis hahram, M.; Milanfar, P.; mage Processing, IEEE Transactions on , Volume: 13 , Issue: 5 , May 2004 ages:677 - 689						
Abstract] [PDF Full-Text (368 KB)] IEEE JNL						
Adaptive alpha-trimmed mean filters under deviations from assumoise model ten, R.; de Figueiredo, R.J.P.; mage Processing, IEEE Transactions on, Volume: 13, Issue: 5, May 2004 ages:627 - 639						
Abstract] [PDF Full-Text (1080 KB)] IEEE JNL						
The Influence of Four Types of Symbol Synchronizers on the Error robability of a PAM Receiver openeclaey, M.; ommunications, IEEE Transactions on [legacy, pre - 1988], Volume: 32, 11, Nov 1984 ages:1186 - 1190  Abstract] [PDF Full-Text (408 KB)] IEEE JNL  A radar detection philosophy debert, W.; offormation Theory, IEEE Transactions on , Volume: 2, Issue: 3, Sep 1956 ages:204 - 221  Abstract] [PDF Full-Text (2448 KB)] IEEE JNL						

ec f c

### 5 Discrimination of shot-noise-driven poisson processes by external c time: Application to radioluminescence from glass

Saleh, B.; Tavolacci, J.; Teich, M.;

Quantum Electronics, IEEE Journal of , Volume: 17 , Issue: 12 , Dec 1981

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[Abstract] [PDF Full-Text (3624 KB)] **IEEE JNL** 

### 6 Combining low-, high-level and empirical domain knowledge for automated segmentation of ultrasonic breast lesions

Madabhushi, A.; Metaxas, D.N.;

Medical Imaging, IEEE Transactions on , Volume: 22 , Issue: 2 , Feb. 2003

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### 7 Sequential testing of sorted and transformed data as an efficient was implement long GLRTs

Marano, S.; Willett, P.; Matta, V.;

Signal Processing, IEEE Transactions on [see also Acoustics, Speech, and Signal Processing Signal Proc Processing, IEEE Transactions on], Volume: 51, Issue: 2, Feb. 2003 Pages: 325 - 337

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Lequesne, B.; Schroeder, T.;

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Liu, J.; Chang, W.; Loncaric, S.;

Nuclear Science, IEEE Transactions on , Volume: 42 , Issue: 4 , Aug 1995

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Sartori, M.A.; Antsaklis, P.J.;

Control Systems Magazine, IEEE , Volume: 12 , Issue: 2 , April 1992

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Shnidman, D.A.;

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# 12 Efficient technique for circle detection using hypothesis filtering ar Hough transform

Lam, W.C.Y.; Yuen, S.Y.;

Vision, Image and Signal Processing, IEE Proceedings- , Volume: 143 , Issue:

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Tsang, K.M.; Billings, S.A.;

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#### 14 Jumping snakes and parametric model for lip segmentation

Eveno, N.; Caplier, A.; Coulon, P.-Y.;

Image Processing, 2003. Proceedings. 2003 International Conference on , Vo

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# 15 Towards direct recovery of shape and motion parameters from ima sequences

Benoit, S.; Ferrie, F.P.;

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